**A.** Suppose for the sake of contradiction that H decides  $ACC_{TM}$ . We describe a decider D for  $HALT_{TM}$ . On input  $\langle M, w \rangle$ , D performs this algorithm:

- 1. Run H on  $\langle M, w \rangle$ . If H accepts, then accept. Otherwise, continue.
- 2. Build a Turing machine N that is identical to M except that the accept and reject states are switched.
- 3. Run H on  $\langle N, w \rangle$ . If H accepts, then accept. Otherwise, reject.

Because all three steps of D halt, D is a decider. Further,

 $D \text{ accepts } \langle M, w \rangle \iff H \text{ accepts } \langle M, w \rangle \text{ or } H \text{ accepts } \langle N, w \rangle$  $\Leftrightarrow M \text{ accepts } w \text{ or } N \text{ accepts } w$  $\Leftrightarrow M \text{ accepts } w \text{ or } M \text{ rejects } w$  $\Leftrightarrow M \text{ halts on } w$  $\Leftrightarrow \langle M, w \rangle \in HALT_{TM}.$ 

Thus D is a decider for  $HALT_{TM}$ . But  $HALT_{TM}$  is undecidable. This contradiction implies that  $ACC_{TM}$  is also undecidable.

[Can you optimize D down to a single invocation of H? Many students did in their solutions.]

**B.A.** Yes. Consider a nondeterministic Turing machine with time complexity t(n) and space complexity s(n). Recall that

$$s(n) = \max_{w:|w|=n} \left( \max_{\text{branches on } w} (\text{space usage of that branch}) \right).$$

But, on each branch, the space usage is at most one more than the time usage. Therefore

$$s(n) \leq \max_{w:|w|=n} \left( \max_{\text{branches on } w} \left( 1 + \text{time usage of that branch} \right) \right)$$
$$= 1 + \max_{w:|w|=n} \left( \max_{\text{branches on } w} \left( \text{time usage of that branch} \right) \right)$$
$$= 1 + t(n).$$

Thus s(n) is  $\mathcal{O}(t(n))$ .

**B.B.** On two occasions we have described a four-tape deterministic Turing machine M for simulating N. The first tape stores the input and hence uses space  $n = \mathcal{O}(t_N(n))$  by the assumption that  $t_N(n) \ge n$ . The second tape simulates N's tape and hence uses space  $s_N(n) =$  $\mathcal{O}(t_N(n))$  by the space-time lemma. The third tape stores the branching pattern of N and hence uses space  $\mathcal{O}(t_N(n))$ . The fourth tape uses space  $\mathcal{O}(1)$ . Hence  $s_M(n)$  is  $\mathcal{O}(t_N(n))$ . Converting the multi-tape M to a single-tape D increases the space usage by a constant multiple. Hence  $s_D(n) = \mathcal{O}(s_M(n)) = \mathcal{O}(t_N(n)).$ 

[Here's an alternative idea. First,  $s_D(n)$  is  $\mathcal{O}(t_D(n))$  by the space-time lemma. Second,  $t_D(n)$  is  $2^{\mathcal{O}(t_N(n))}$ . Third,  $2^{\mathcal{O}(s_N(n))}$  is  $2^{\mathcal{O}(t_N(n))}$  by the space-time lemma. Is there any way to combine these facts to get a bound?]

**C.B.** This was a homework problem. The language is decidable and hence recognizable and co-recognizable.

**C.C.** Suppose for the sake of contradiction that the language is decidable by a decider H. Then one can build a decider D for the language  $\{\langle M \rangle : M \text{ accepts } \epsilon\}$ . (Briefly, D runs H on  $\langle M, \epsilon \rangle$ ). If H rejects, then D rejects. If H accepts, then D runs M on  $\epsilon$  and outputs whatever M outputs.) But the latter language is undecidable by Rice's theorem. This contradiction shows that the language in question is undecidable. It is recognizable, because a recognizer could simply run M on  $\epsilon$  and accept whenever M halted. Because the language is undecidable and recognizable, it cannot be co-recognizable.

**C.D.** For brevity, call the language A. I claim that A is decidable and hence recognizable and co-recognizable. To support this claim, we design a decider D that, on input  $\langle M, c \rangle$ , does the following computation.

- 1. For each input w such that  $|w| \le c+1$ :
  - (a) Simulate M on w for up to c steps.
  - (b) If M does not halt on w in c or fewer steps, then reject.
- 2. Accept.

This D is a decider because its loop fires finitely many times, doing finitely much work per firing. Now fix an  $\langle M, c \rangle$ . For brevity, call a string w short if  $|w| \leq c + 1$ . Suppose that Drejects  $\langle M, c \rangle$ . Then it must have found a w on which M does not halt in c or fewer steps, so  $\langle M, c \rangle \notin A$ . Conversely, suppose that D accepts  $\langle M, c \rangle$ . Then M halts on all short w in c or fewer steps. Let x be any input to M such that |x| > c + 1, and let w be the string consisting of the first c + 1 characters in x. Then M's behavior on input x is identical to M's behavior on input w, because M halts before it can reach the latter characters in x. So, because M halts on all short w in c or fewer steps, it halts on all inputs x in c or fewer steps. So  $\langle M, c \rangle \in A$ . Thus D decides A.

**C.E.** The language is undecidable by Rice's theorem. I don't know more than that. So the recognizable and co-recognizable adjectives were removed from grading.

**C.F.** Any M can be modified into an N that has a disconnected state, simply by adding a state that loops on itself. Therefore the language consists of all Turing machine encodings  $\langle M \rangle$ . In the jargon of Rice's theorem, it is a trivial property of recognizable languages. It is decidable and hence recognizable and co-recognizable.

**C.G.** The language is undecidable by Rice's theorem. It is recognizable, because a recognizer could simply run M on  $\langle M \rangle$  and output whatever M outputted. Because the language is undecidable and recognizable, it cannot be co-recognizable.

**C.H.** The language is decidable and hence recognizable and co-recognizable. All of our algorithms for processing such pairs — for example, the recognizer for  $ACC_{TM}$  — implicitly perform this check at the start of their computation.