

**A.A.** The desired vector is  $\vec{w} - \vec{v} = \langle -6, 0, 3 \rangle$ .

**A.B.** The projection is

$$\text{proj}_{\vec{w}} \vec{v} = \frac{\vec{v} \cdot \vec{w}}{\vec{w} \cdot \vec{w}} \vec{w} = \frac{-8 + 1 - 2}{16 + 1 + 4} \langle -4, 1, 2 \rangle = \frac{-3}{7} \langle -4, 1, 2 \rangle = \left\langle \frac{12}{7}, \frac{-3}{7}, \frac{-6}{7} \right\rangle.$$

**A.C.** The desired vector is

$$3 \frac{\vec{v}}{|\vec{v}|} = \frac{3}{\sqrt{6}} \langle 2, 1, -1 \rangle = \left\langle \sqrt{6}, \frac{3}{\sqrt{6}}, \frac{-3}{\sqrt{6}} \right\rangle.$$

**B.** No, it need not be true that  $\vec{v} = \vec{u}$ . For example, reducing the angle between  $\vec{v}$  and  $\vec{w}$  can be compensated by reducing the length of  $\vec{u}$ . An explicit example is

$$\langle 0, 1, 0 \rangle \times \langle 0, 0, 1 \rangle = \langle 1, 0, 0 \rangle = \langle 0, 1, 1 \rangle \times \langle 0, 0, 1 \rangle.$$

An even simpler example, which a student devised, is  $\vec{u} = \vec{0}$  and  $\vec{v} = \vec{w} \neq \vec{0}$ .

**C.A.** Using L'Hopital's rule once, we have

$$\lim_{t \rightarrow 0} \vec{x}(t) = \left( \lim_{t \rightarrow 0} 1 + t^2, \lim_{t \rightarrow 0} \frac{\sin t}{t} \right) = \left( 1, \lim_{t \rightarrow 0} \frac{\cos t}{1} \right) = (1, 1).$$

**C.B.** No,  $\vec{x}$  is not continuous at  $t = 0$ , because it is not even defined there.

**C.C.** By the quotient rule,

$$\vec{x}'(t) = \left( \frac{d}{dt} (1 + t^2), \frac{d}{dt} \left( \frac{\sin t}{t} \right) \right) = \left( 2t, \frac{t \cos t - \sin t}{t^2} \right).$$

**C.D.** Anti-differentiation by substitution gives

$$\int \vec{y}(t) dt = \left( \int t^3 dt, \int \frac{2t}{\sqrt{t^2 + 1}} dt \right) = \left( \frac{1}{4} t^4 + C_1, 2(t^2 + 1)^{1/2} + C_2 \right).$$

[It is important that each component anti-derivative have a “+ C”. It is important that the two constants are allowed to be different.]

**D.A.** Following our usual method, we write

$$y = x^2 \quad \Rightarrow \quad r \sin \theta = r^2 \cos^2 \theta \quad \Rightarrow \quad r = \frac{\sin \theta}{\cos^2 \theta}.$$

**D.B.** [It helps to draw a picture.] We need  $\theta$  to go from 0, where  $r = 0$ , to  $\pi/2$ , where  $r$  is undefined. Then we need  $\theta$  to go from  $\pi/2$  to  $\pi$ , where  $r = 0$  again. So the answer is  $[0, \pi/2) \cup (\pi/2, \pi]$ . It would also be fine to leave off one of those endpoints.

**E.A.** [Instead of drawing, I'll describe my thought process.] First,  $(\cos t, \sin t)$  plots as the unit circle. So  $(\cos t, 2 \sin t)$  plots as the ellipse of width 2 and height 4. Then  $(1 + \cos t, 2 \sin t)$  plots as that ellipse shifted right by 1, so that it is centered at  $(1, 0)$ .

**E.B.** The arc length is

$$\int_0^{2\pi} |\vec{x}'(t)| dt = \int_0^{2\pi} |(-\sin t, 2 \cos t)| dt = \int_0^{2\pi} \sqrt{\sin^2 t + 4 \cos^2 t} dt.$$

We can do a little more algebra on the integrand, but it doesn't really help. We can't compute the integral symbolically. [My intent, in writing this problem, was just to see whether students could set up the arc length integral. See the nearly identical example in the Mathematica notebook `calculusCurves.nb` on our course web site.]

**F.** [Draw a picture.] A normal vector to the hyperplane is  $\vec{n} = \langle a, b, c, d \rangle$ . Let  $\vec{x}$  be any point on the hyperplane. Then the equation of the hyperplane says that  $\vec{n} \cdot \vec{x} = e$ . The distance from  $\vec{p}$  to the hyperplane is the length of the projection of the vector  $\vec{p} - \vec{x}$  onto  $\vec{n}$ :

$$\begin{aligned} |\text{proj}_{\vec{n}}(\vec{p} - \vec{x})| &= \left| \frac{\vec{n} \cdot (\vec{p} - \vec{x})}{\vec{n} \cdot \vec{n}} \vec{n} \right| \\ &= \left| \frac{\vec{n} \cdot \vec{p} - \vec{n} \cdot \vec{x}}{|\vec{n}|} \frac{\vec{n}}{|\vec{n}|} \right| \\ &= \frac{|\vec{n} \cdot \vec{p} - \vec{n} \cdot \vec{x}|}{|\vec{n}|} \\ &= \frac{|ap_1 + bp_2 + cp_3 + dp_4 - e|}{\sqrt{a^2 + b^2 + c^2 + d^2}}. \end{aligned}$$